

Synchronized Position Hold, Engage, Reorient, Experimental Satellites

> Overview April 2002

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#### What is SPHERES?

#### SPHERES...

- Is an ISS internal testbed for the development and testing of formation flying and other multi-spacecraft control algorithms
- Consists of three self-contained eight-inch diameter freefloating satellites which perform the various algorithms
- Uses data collected from one test session to build the algorithms for the next test session
- Is an interactive testbed -- ISS crew members command & observe the programmed maneuvers



### SPHERES Team

#### Who's involved:

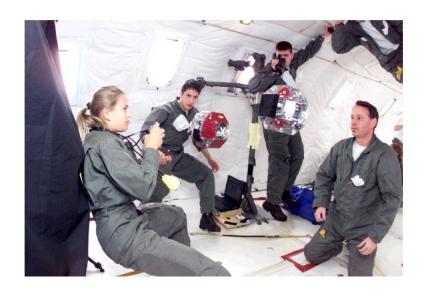
- DARPA Orbital Express Program
  - Research and flight opportunity sponsor
- Massachusetts Institute of Technology
  - Principal Investigator: Prof. David Miller
  - Prototype design and testing
  - Algorithm development
- Payload Systems Inc.
  - Flight hardware design, fabrication & testing
  - Flight hardware integration & safety
- DoD Space Test Program and ISS Payload Integration Office
  - Flight manifest on ISS
  - Payload integration & safety support





### Science Motivation

- To reduce cost and improve performance, many missions are considering distributed spacecraft architectures
- Routine and autonomous formation flight is essential to the operation of these missions
- Long duration µ-g is impossible to simulate in the laboratory
- Therefore, an on-orbit testbed is needed to conduct research in μ-g for maturing these technologies

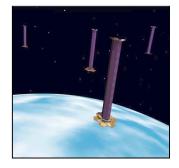




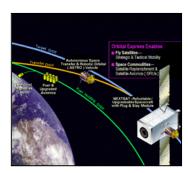
**StarLight** 



**Terrestrial Planet Finder** 



TechSat 21



**Orbital Express** 



# Science Objective

- SPHERES will serve to mature autonomous satellite formation flight, rendezvous and docking algorithms in a long duration, micro-gravity environment.
  - Allow for the interchange of control algorithms, the acquisition and analysis of data, and a truth measure
  - Demonstrate key close proximity formation flight and docking maneuvers
  - Demonstrate autonomous fault diagnosis and recovery
  - Ensure the adaptability of control algorithms to future formation flight missions





- Testing in the internal volume of ISS permits rapid algorithm iteration and dramatically reduces mission risk
  - Failed algorithm does not result in the loss of the payload
  - More likely to pursue ambitious test objectives
- ISS provides the benefits of a research laboratory-like setting, but in the microgravity environment
  - Human-in-the-loop research will allow testing to be guided along more productive routes
  - Consumables can be replenished
  - Video and crew commentary will provide valuable feedback to research team
  - Through iterative algorithm development, use last week's results to develop this week's tests







- SPHERES on ISS for two crew rotations
  - Ascent flight ISS-12A.1 (STS-116) May 2003
  - Re-supply flight ISS-13A.1 (STS-118) for replacement of consumables
  - Descent flight ISS-15A (STS-119) January 2004
- Operation time
  - Allocated 24 hours operation time (twelve 2-hour sessions with option for eight 3-hour or six 4-hour sessions)
  - Setup and tear down time not included in total operations time
- Initial stowage requirements
  - Three SPHERES satellites
  - Five Ultrasound (US) beacons
  - Laptop transmitter
  - Consumables (CO<sub>2</sub> tanks and battery packs)



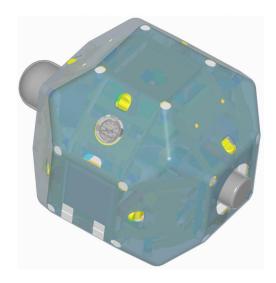




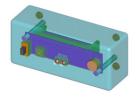
# Hardware Components

- SPHERES consists of three "satellites" eight-inches in diameter
  - Each satellite is self-contained with power (AA batteries), propulsion (CO<sub>2</sub> gas), computers, and navigation equipment
  - The satellites communicate with each other and an ISS laptop through a low-power wireless (RF) link
  - Operational volume is 6' x 6' x 6' (up to 10' x 10' x 10' is possible)
- Five ultrasound beacons located in the SPHERES work envelope act as a navigation system
  - Each beacon is self-contained and uses a single AA battery
  - A single beacon is approximately the size of a pager

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Satellite

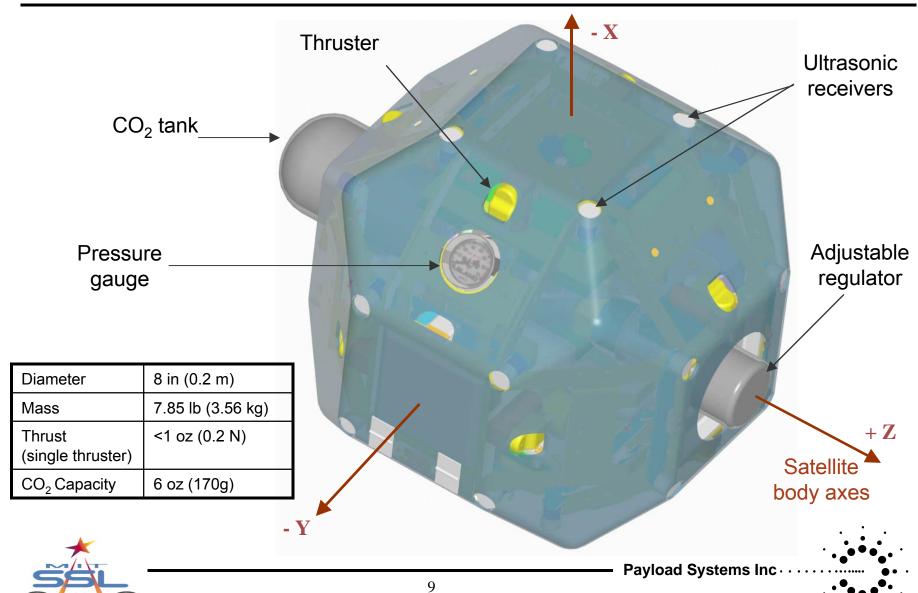


Ultrasound (US) beacon



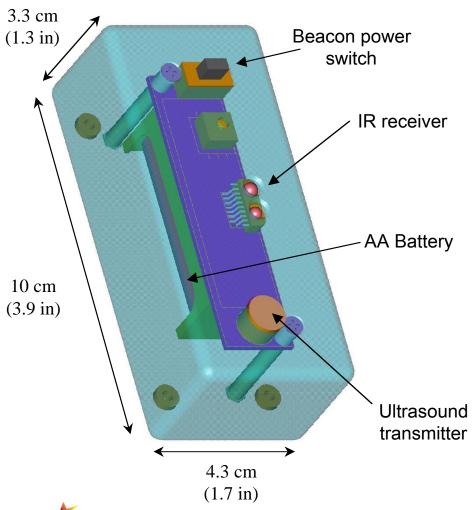


## SPHERES Satellite





### Ultrasound Beacon Structure



- Beacon components
  - One Infrared (IR) receiver
  - One US transmitter
  - One AA battery
  - Associated circuitry

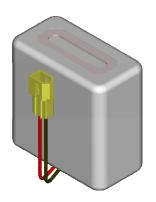
Mass	0.25 lb (113 g)
Dimensions	1.3 x 3.9 x 1.7 in (3.3 x 10.0 x 4.3 cm)
Battery lifetime	>24hrs
US emitter frequency	40 kHz





### Consumables





Replacement CO<sub>2</sub> tanks and battery packs

#### CO<sub>2</sub> tanks

- Contain liquid CO<sub>2</sub>
- Liquid is expanded to gas for expulsion
- Mass: 517 g
- Capacity: 170 g CO<sub>2</sub>
- Provides ΔV of 13.2 m/s

#### Batteries

- 16 AA x (1.5V) alkaline batteries housed in two battery packs
- Satellites run for approximately 90 min on two battery packs





# **Operational Configurations**

- Mode 1: Single satellite operations examples
  - Long term station-keeping
  - Minimum propellant maneuvers through pre-determined profiles
    - Isolated multidimensional rotation, multidimensional translation
    - Combined rotation & translation
- Modes 2 and 3: Multiple satellite operations examples (two or three satellites)
  - Docking
  - Topological orientations
    - Independent control
    - · Collision avoidance
    - Hierarchical control (leader-follower)
    - Distributed control (consensus)



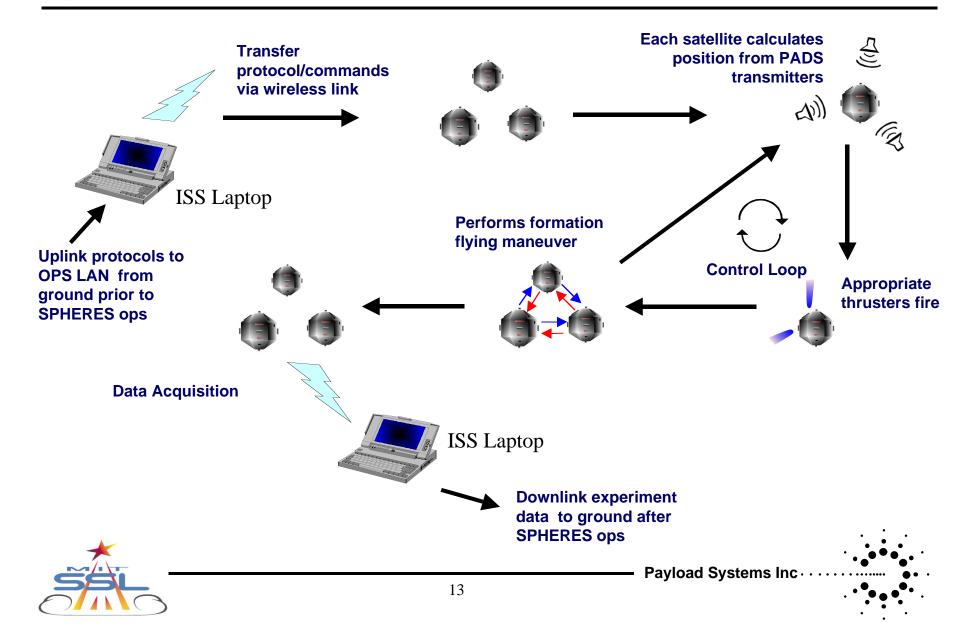


Example configurations on the KC-135





# **SPHERES** Typical Test Session Flow Chart

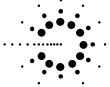




# Prototype Testing on KC-135









# Prototype Testing on KC-135









### For More Information

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